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6.0/4.0 VU Formale Methoden der Informatik 185.291 March 24, 2025			
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Block 1.) Recall from the lecture the **HALTING** problem:

HALTING

INSTANCE: A non-empty program Π that takes a string as input, a string I .

QUESTION: Does Π terminate on I .

Consider now the following decision problem:

EQUAL

INSTANCE: Program Π that is guaranteed to terminate, takes a natural number (excluding zero) as input and returns a natural number or zero as output.

QUESTION: Do there exist natural numbers n_1, n_2 , such that $n_1 + n_2 = \Pi(n_1) * \Pi(n_2)$?

1.a) Let Π_{int} be the decision procedure that does the following:

- Π_{int} takes as input a program Π , a string I , and a natural number n .
- Π_{int} emulates the first n steps of the run of Π on I . If Π terminates on I within n steps, then Π_{int} returns true. Otherwise, Π_{int} returns false.

The following describes a reduction from **HALTING** to **EQUAL**. Given an arbitrary instance (Π, I) of **HALTING**, we construct an instance (Π') of **EQUAL** as follows:

```

Boolean  $\Pi'$  (Int  $n$ )
if ( $n < 2$ ) return 1;
if  $\Pi_{\text{int}}(\Pi, I, n)$  return  $n + 1$ ; //  $\Pi$  and  $I$  are hard-coded
return 0;

```

Show the correctness of the reduction above, i.e., show that (Π, I) is a positive instance of **HALTING** \iff (Π') is a positive instance of **EQUAL**.

(9 points)

1.b) Please answer the following questions and explain your answers:

- Is **EQUAL** undecidable?
- Is **EQUAL** semi-decidable?

(6 points)

Block 2.)

- 2.a)** Suppose a, b, c are unsigned integers in the programming language C and $a \leq b$. Which problem can occur with a C statement $c = (a+b)/2$? What is a simple solution to the problem? **(2 points)**

2.b) Use the sparse method to translate the following formula φ^E

$$\neg(a \dot{=} b \wedge a \not\dot{=} c \rightarrow ((a \dot{=} d \wedge e \not\dot{=} f \wedge g \not\dot{=} h) \vee g \not\dot{=} i \vee h \not\dot{=} j \vee (b \not\dot{=} c \wedge g \dot{=} i \wedge i \not\dot{=} j)))$$

into a propositional formula φ^p such that φ^E is E-satisfiable if and only if φ^p is satisfiable. Simplify your formula before you construct the propositional skeleton and the transitivity constraints. In the simplifications steps, indicate the simple contradictory cycles and the pure literals.

Present an E-model for φ^E in a formally correct way.

(13 points)

Block 3.)

3.a) Let p be the following IMP program, containing the integer-valued program variables x, y, z :

```
 $x := n; y := 0; z := 0;$   
while  $x > 0$  do  
   $z := z - 3 * x;$   
   $y := y + 6 * x;$   
   $x := x - 1$   
od
```

Give a variant and inductive invariant for the loop in p and prove the validity of the total correctness triple:

$$[n > 0] \quad p \quad [y + 2 * z = x]$$

(10 points)

3.b) Consider the following rule in Hoare logic:

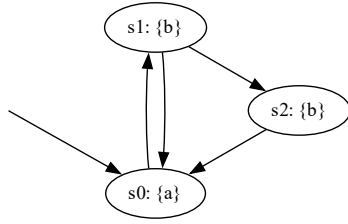
$$\frac{}{\{A\} \mathbf{x} := \mathbf{y}; \mathbf{abort}; \mathbf{x} := \mathbf{y} \{B\}}$$

where A, B are arbitrary assertions and x, y are integer-valued IMP program variables. Is this rule sound? If yes, give a formal proof. Otherwise, give a counterexample and justify your answer.

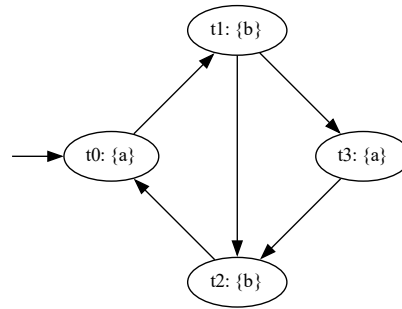
(5 points)

Block 4.) 4.a) Consider the Kripke structures M_1 and M_2 . The initial state of M_1 is s_0 and the initial state of M_2 is t_0 .

Kripke structure M_1 :



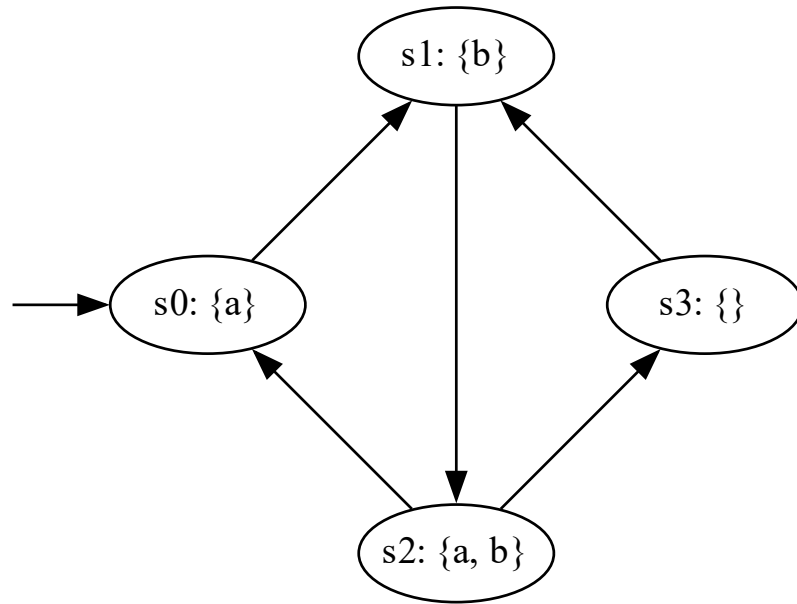
Kripke structure M_2 :



- i. Check whether M_2 simulates M_1 , i.e., provide a simulation relation that witnesses $M_1 \preceq M_2$, or briefly explain why M_2 does not simulate M_1 .
- ii. Check whether M_1 simulates M_2 , i.e., provide a simulation relation that witnesses $M_2 \preceq M_1$, or briefly explain why M_1 does not simulate M_2 .

(4 points)

4.b) Consider the following Kripke structure M :



For each of the following formulae φ ,

- indicate whether the formula is in LTL, CTL, and/or CTL*, and
- list the states s_i on which the formula φ holds; i.e. for which states s_i do we have $M, s_i \models \varphi$?
(If φ is a path formula, list the states s_i such that $M, s_i \models \mathbf{A}\varphi$.)

φ	LTL	CTL	CTL*	States s_i
$\mathbf{X}[a \mathbf{U} b]$	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
$\mathbf{A}\mathbf{X}b$	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
$\mathbf{E}\mathbf{G}(a \vee b)$	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
$\mathbf{F}(\neg a \wedge \neg b)$	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	
$(\mathbf{E}\mathbf{X}a) \wedge \mathbf{X}\neg b$	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	

(5 points)

4.c) Recall that a LTL formula φ is *satisfiable* if there exists a Kripke structure M and a path π in M such that $M, \pi \models \varphi$. In this case we call the pair (M, π) a *model* of φ .

- i. Is there a satisfiable LTL formula φ such that every model of φ has at most three states?
- ii. Is there a satisfiable LTL formula φ such that every model of φ has at least three states?

For each question, you should either

- Construct a satisfiable LTL formula φ such that every model of φ has at most/least three states and briefly explain why this is the case.

or

- Prove that no such formula exists by showing that every satisfiable LTL formula φ has a model with more/fewer than three states.

(6 points)